

# CMPT 983

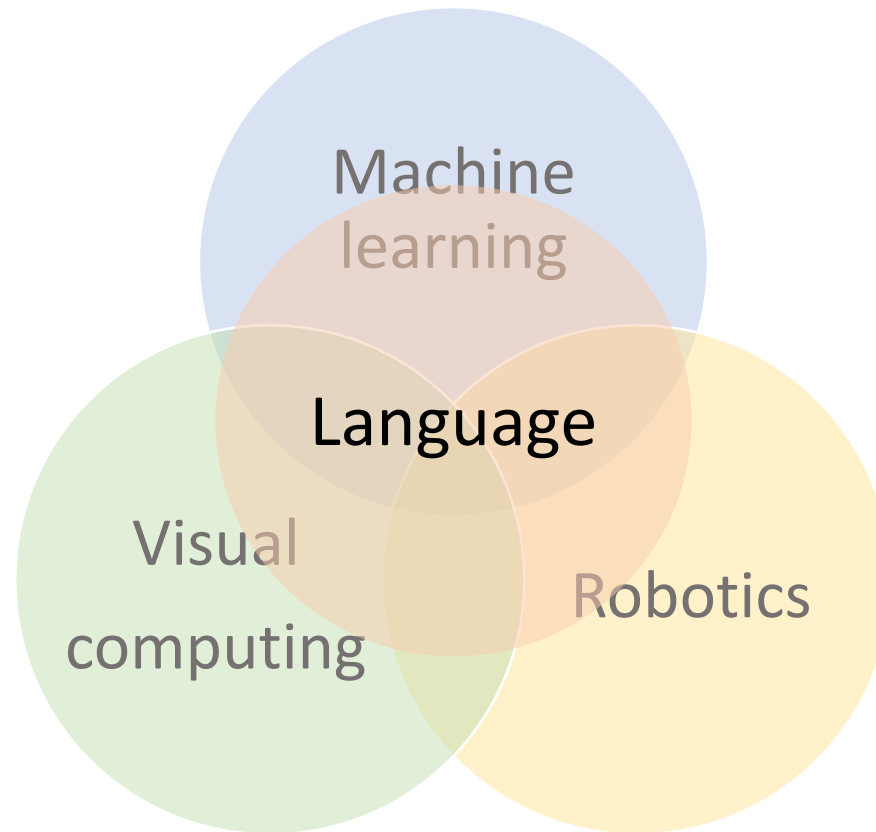
Grounded Natural Language Understanding

April 15, 2021

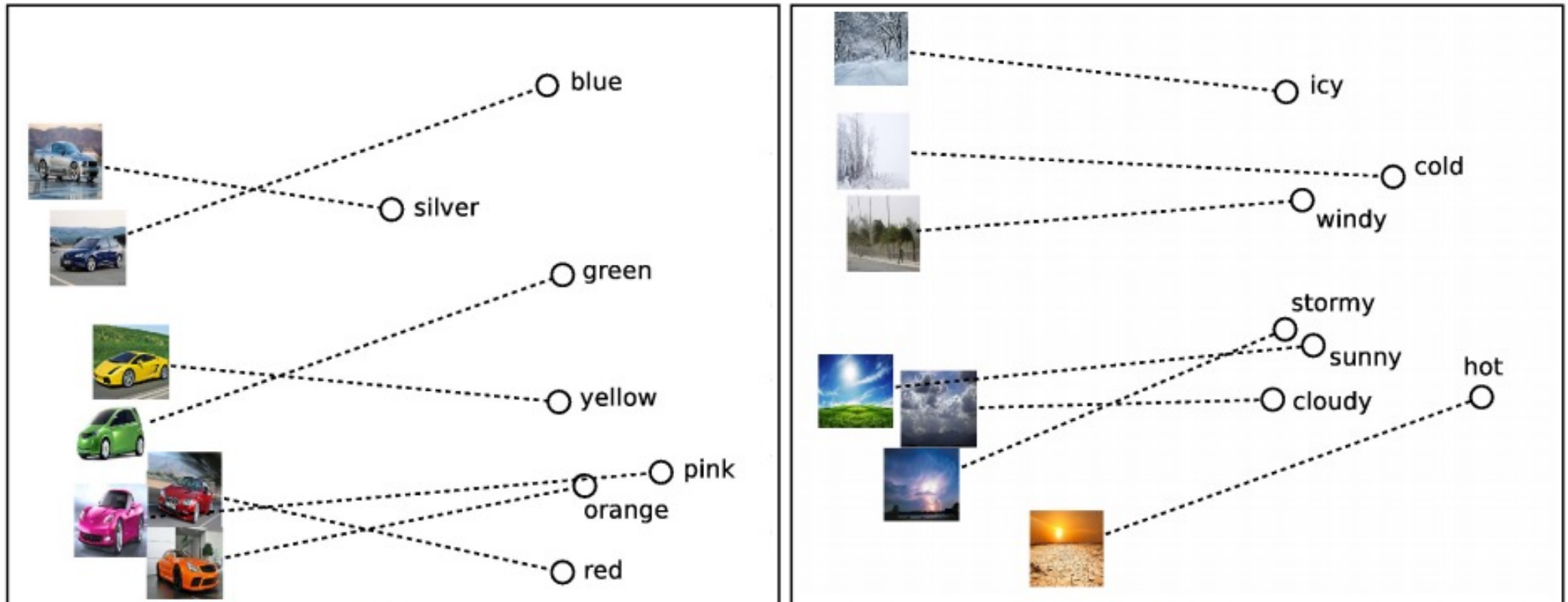
Conclusion

# Grounded natural language understanding

- Lightning tour of topics at the intersection of language and machine learning, visual computing and robotics



# Multimodal Embeddings



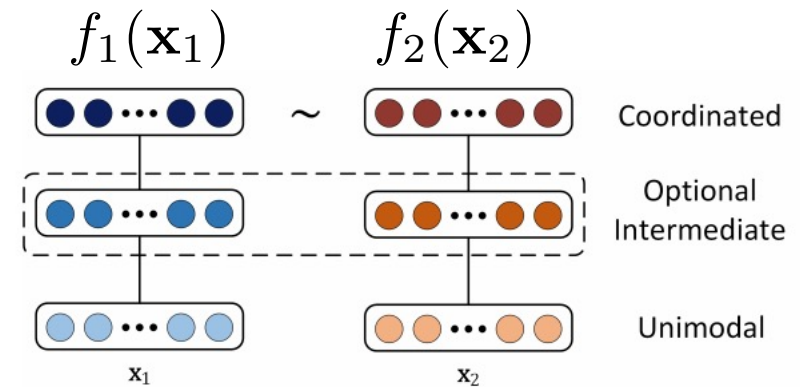
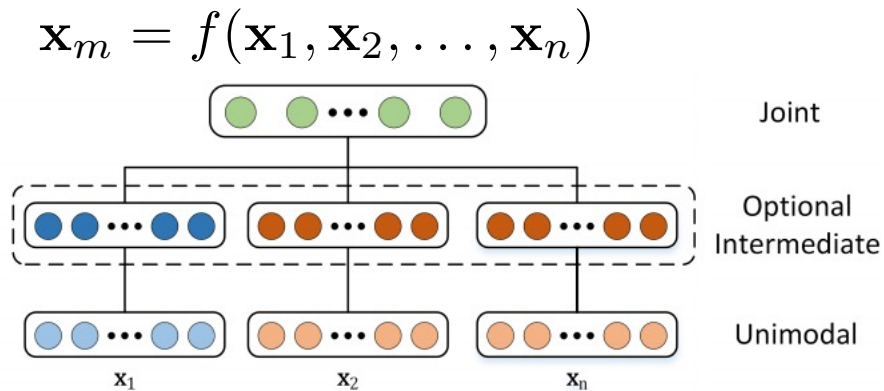
“Unifying Visual-Semantic Embeddings with Multimodal Neural Language Models”  
[Kiros, Salakhutdinov, Zemel TACL 2015]

# Multimodal representations

- Joint vs Coordinated representations
  - Joint: Autoencoder + Fusion (e.g. concat)
  - Coordinated: CCA, joint embeddings

Correct label (more similar)    Other labels (less similar)

$$\mathcal{L}_C(\mathbf{W}, \mathbf{U}, I_i, y_i) = \sum \max\{0, \alpha - \underbrace{D(\Psi(I_i), \mathbf{u}_{y_i})}_{\text{Correct label}} + \underbrace{D(\Psi(I_i), \mathbf{u}_{y_c})}_{\text{Other labels}}\}$$

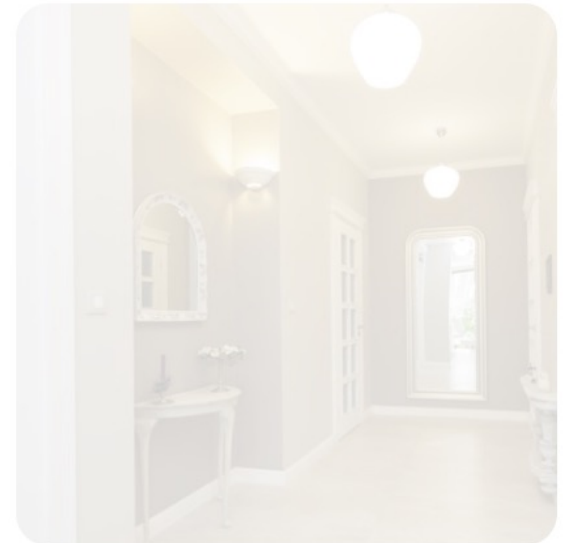


- Useful for retrieval, translation

# Attention

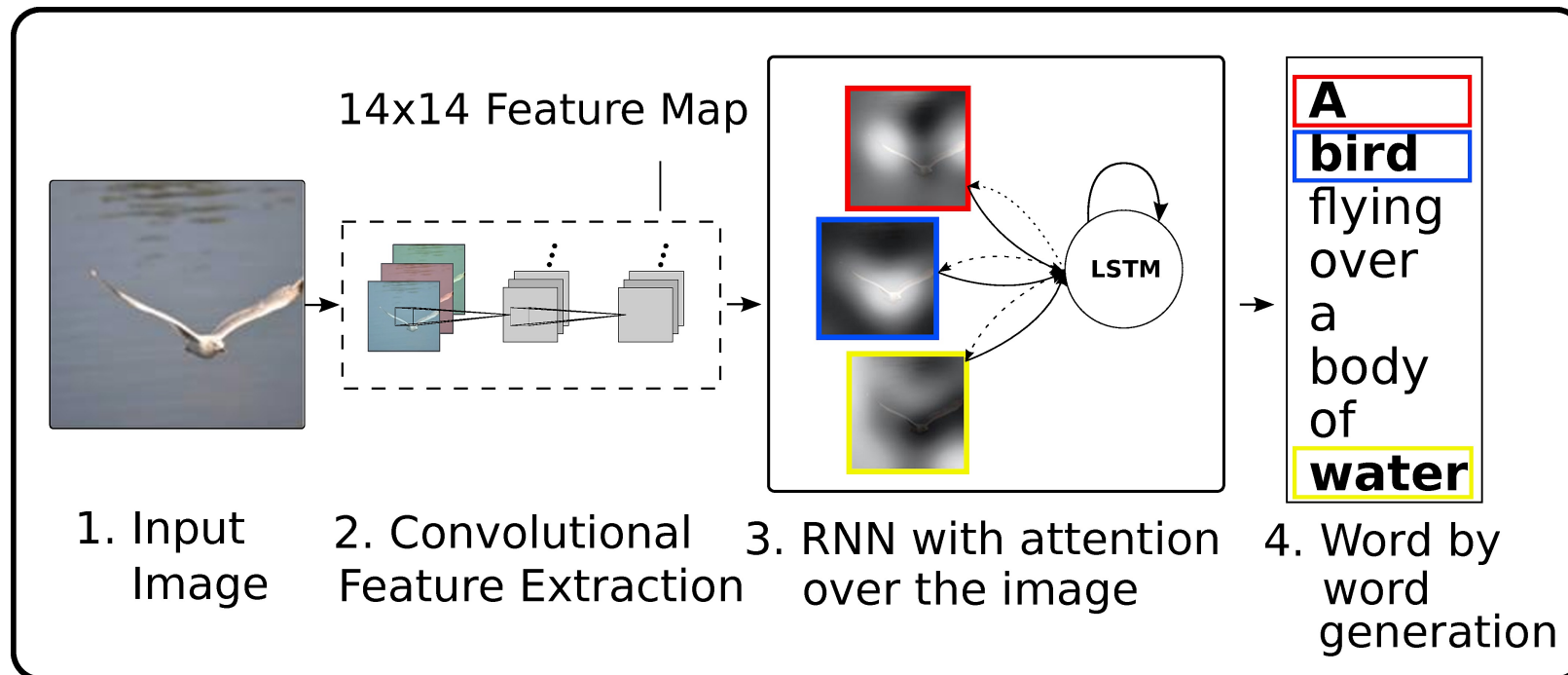
- Not every part of the input given the task context

Exit the bathroom. Turn left and exit the room using the door on the left. Wait there.



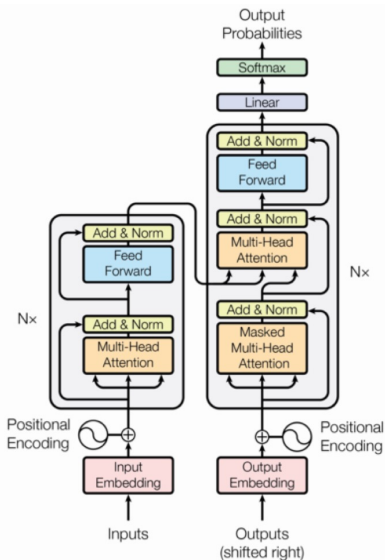
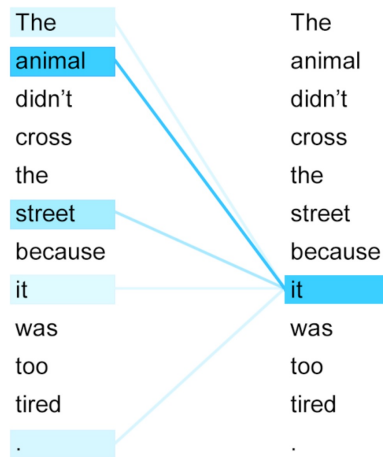
# Attention

- Used for many vision and language tasks
- Including **captioning** and understanding **referring expressions**
- Representation that **weighs** different parts of the input differently



# Attention

- Mathematically: weighted sum  $\hat{v} = \sum_{i=1}^k \alpha_i v_i$
- Types of attention
  - Different ways to compute weight / similarity
  - Hard vs Soft
- Query-key-value view of attention
- Self-attention and transformers



Attention function,  $f$

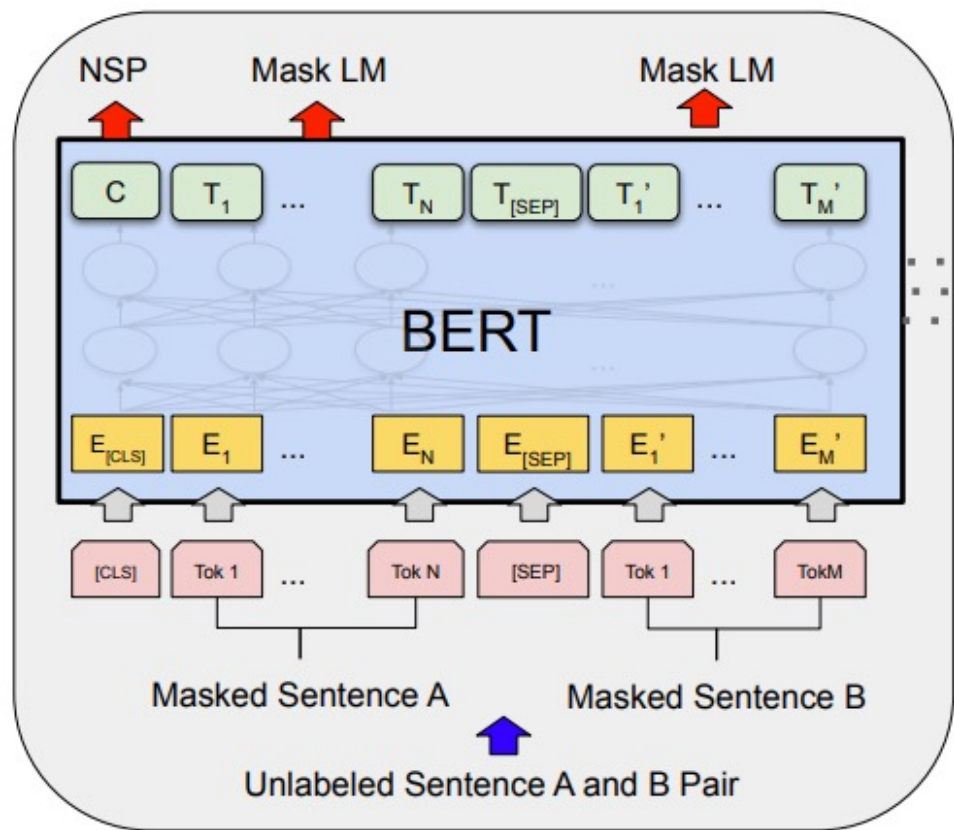
$$a_i = g(k_i, q)$$
$$\alpha = \text{softmax}(a)$$
$$\hat{c} = \sum_{i=1}^k \alpha_i v_i$$

- Scaled dot-product attention:

$$g(c_i, z) = z^T c_i / \sqrt{d}$$

# Pretraining

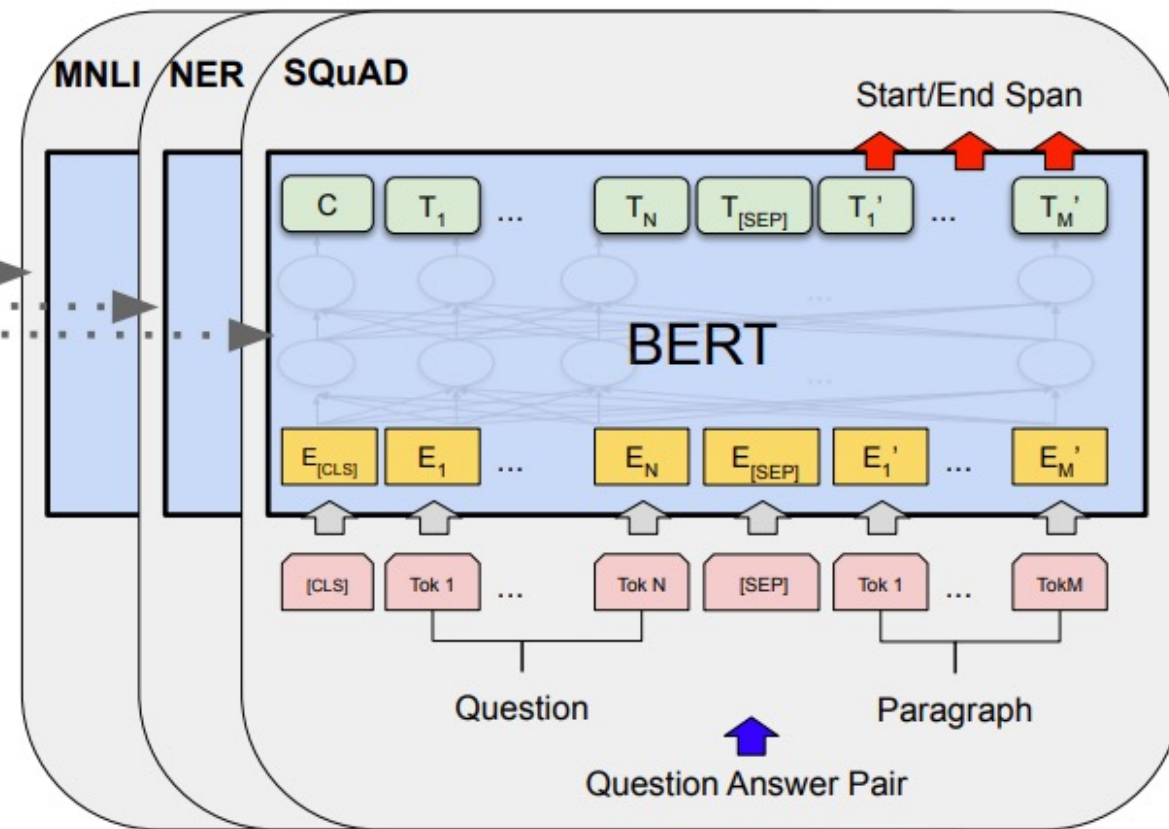
Big pile of unannotated data!  
Lots of resources to train!



Pre-training

Task specific

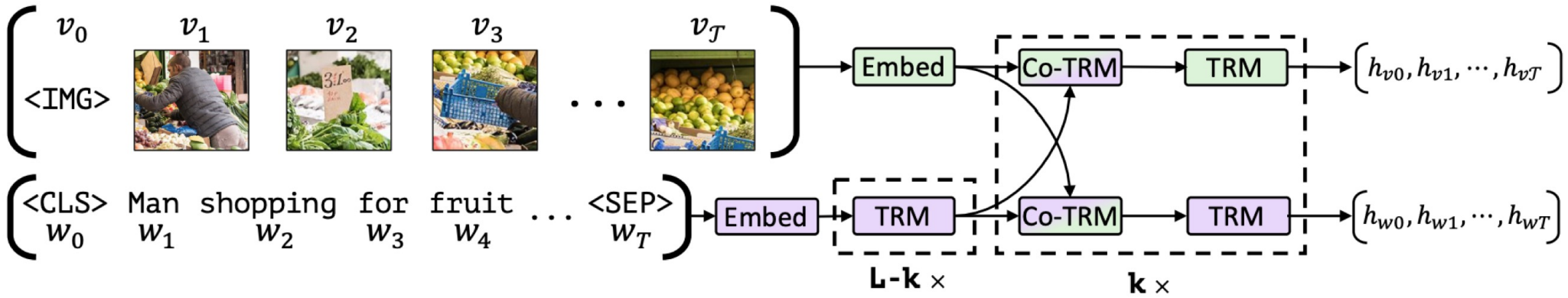
Small amount of annotated data  
Start with pre-trained model



Fine-Tuning

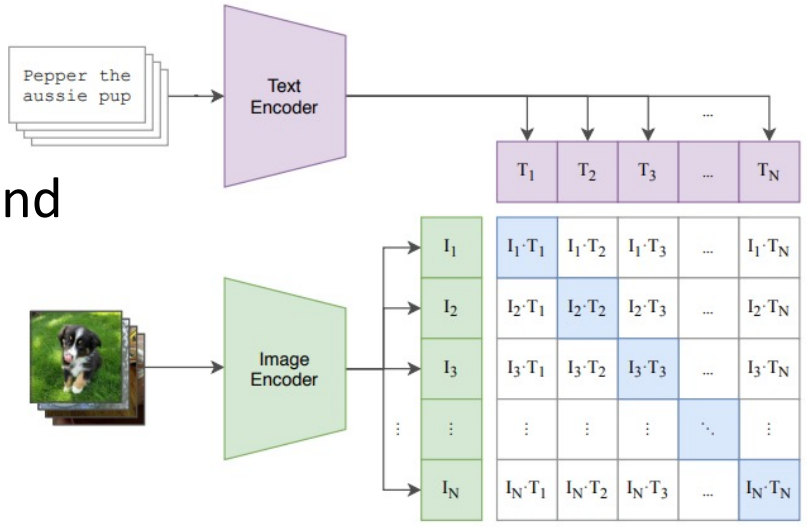


# Pretraining and masked multimodal models



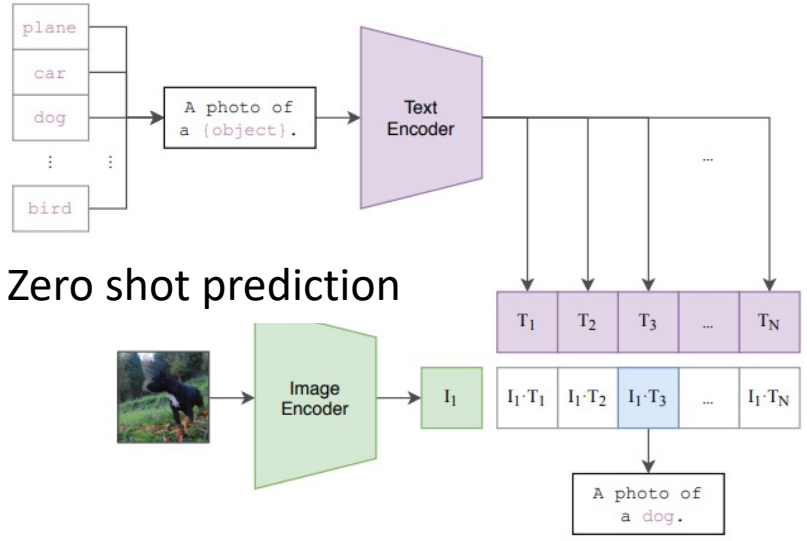
ViLBERT, Lu et al, NeurIPS 2019

## Contrastive pretraining



Does the **image** and **text** pair match?

## Create classifier by generating captions and encoding



## Zero shot prediction

CLIP, Radford et al, 2021

# Structure and compositionality

- Compositionality

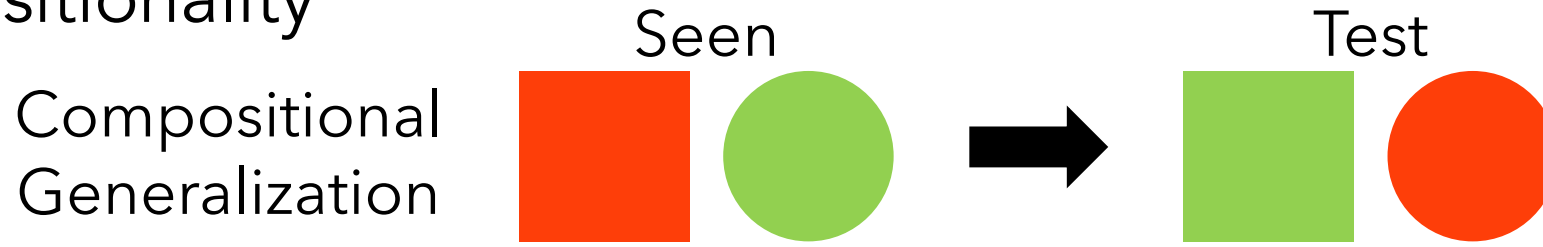
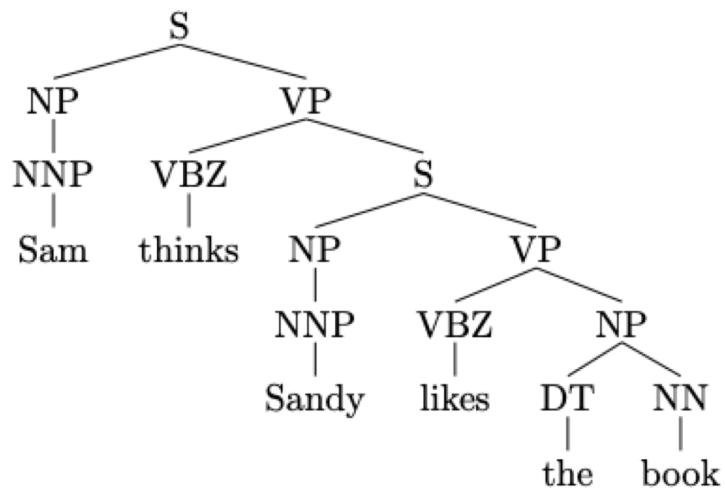


Image credit: Stefan Lee

- Structured representations for compositionality

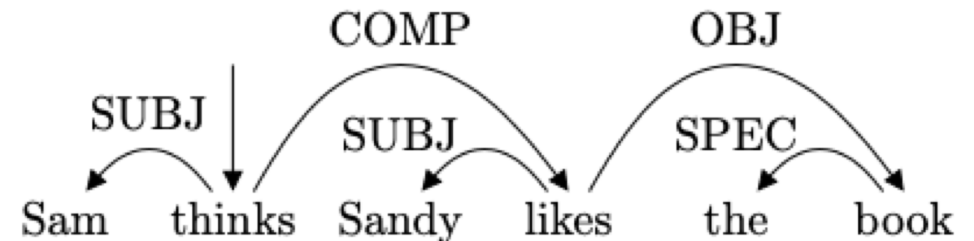
## Constituency Parse Tree

Hierarchical



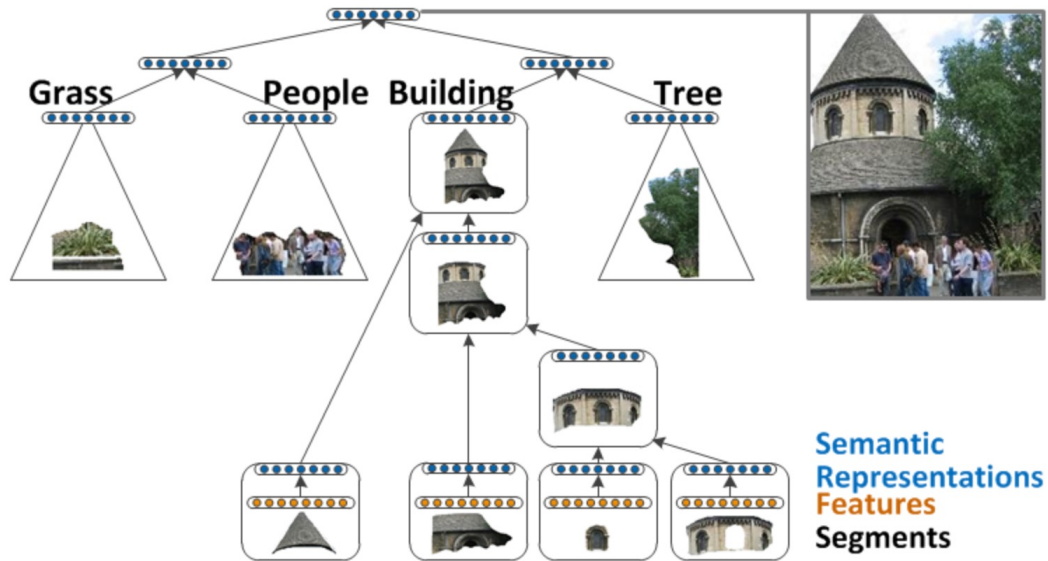
## Dependency Parse

Relational

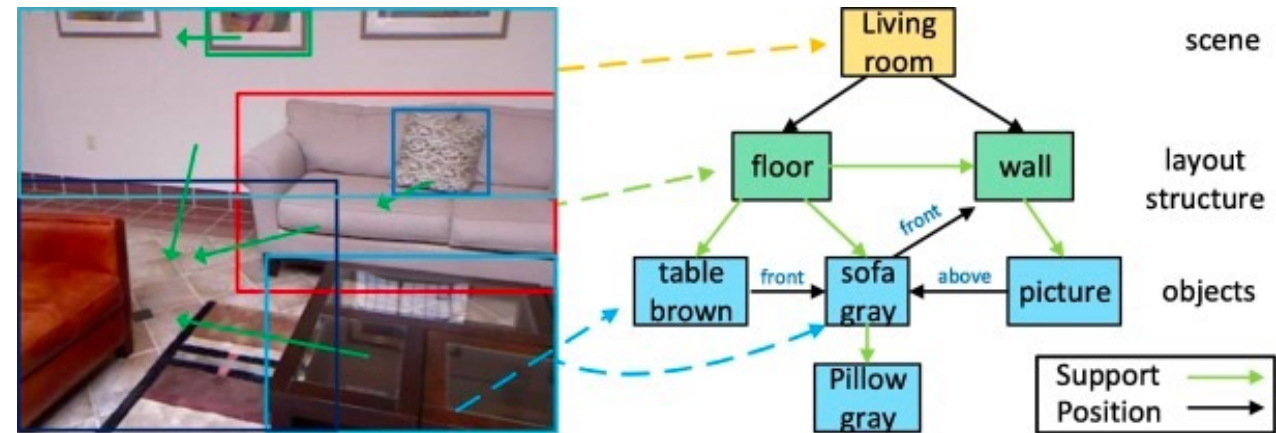


# Structured representation of images

## Scene Parse Tree Hierarchical



## Scene Graph Relational



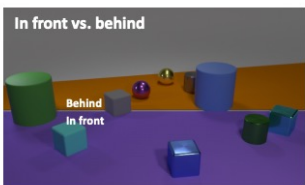
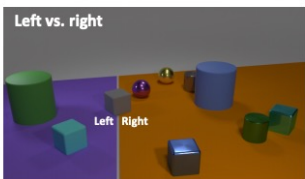
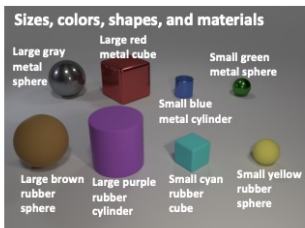
Socher, Lin, Ng, and Manning, "Parsing Natural Scenes and Natural Language with Recursive Neural Networks", ICML 2011

Yang, Liao, Ackermann, and Rosenhahn, "On support relations and semantic scene graphs", ISPRS Journal of Photogrammetry and Remote Sensing, 2017

# Semantic parsing

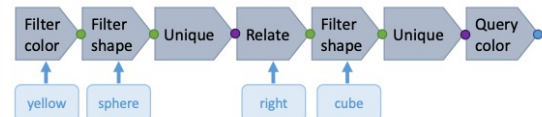
- Parse natural language into programs
- Use in VQA

## Shape and attributes



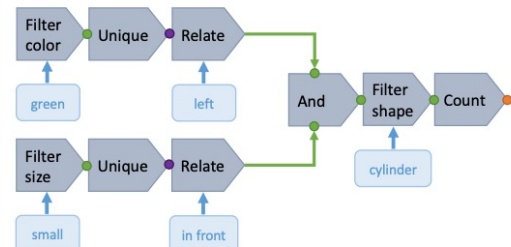
## Programs: formed from composable modules

Sample chain-structured question:



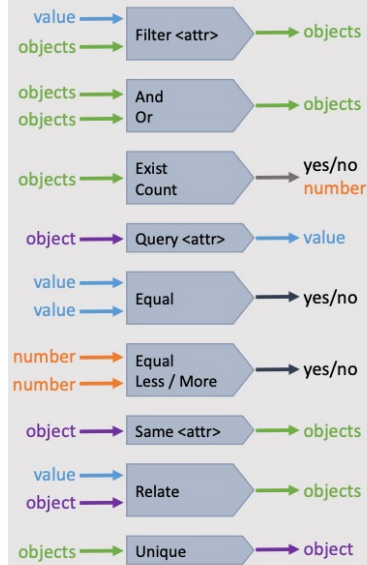
What color is the cube to the right of the yellow sphere?

Sample tree-structured question:

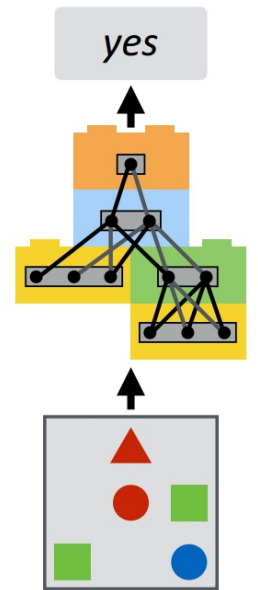
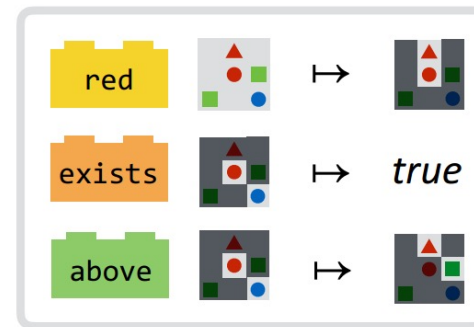


How many cylinders are in front of the small thing and on the left side of the green object?

CLEVR function catalog



Is there a red shape above a circle?



Neural module networks, Andreas et al, CVPR 2016

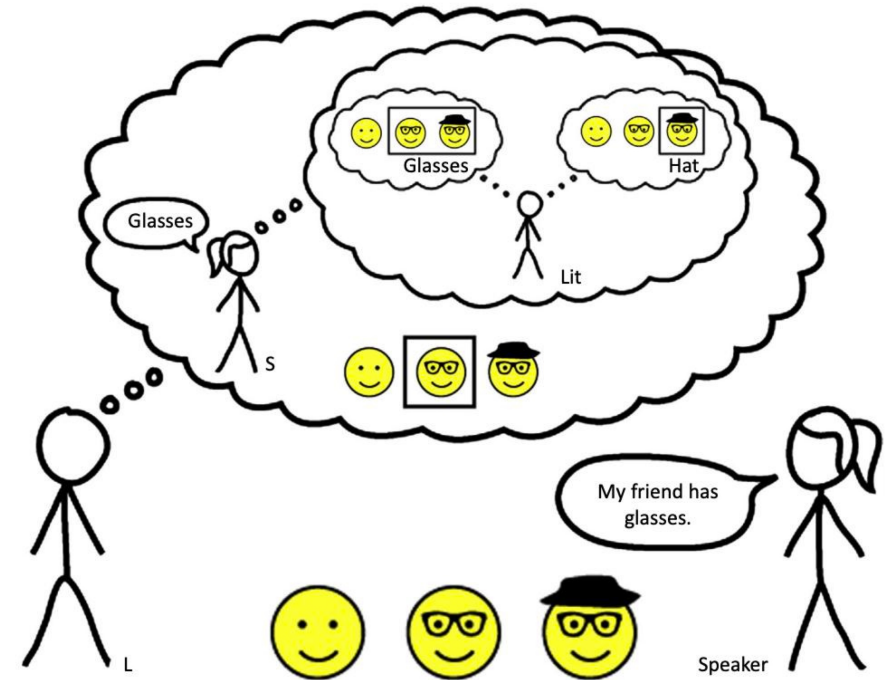
Relations

Generated language

CLEVR dataset, Johnson et al, 2017

# Speaker-listener models

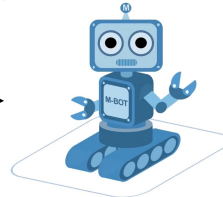
- Need to model other party
- Rational Speech Acts (RSA)
- Used in referring expression generation + comprehension
- Looked at ShapeGlot and emergent communications



Goodman and Frank, 2016

# Instruction following

Exit the bedroom. Turn left down the hall and stop in the kitchen.



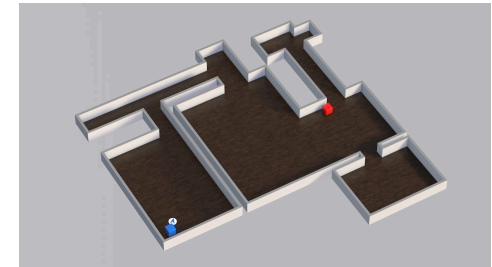
- How to train agent to **follow instructions**?
- Can the agent **learn language** through interacting with the environment?

Observations

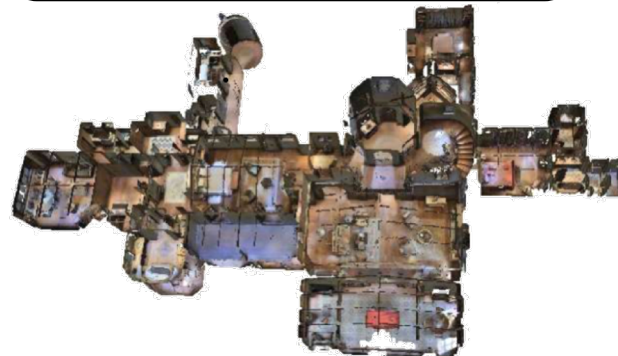


**Agent**

Actions

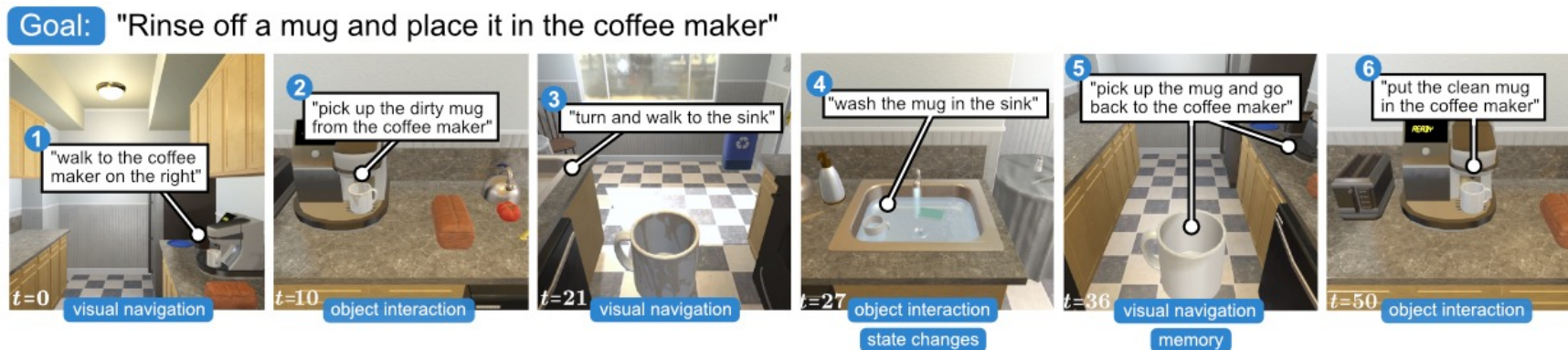


**Environment**



# Instruction following (RoboNLP)

- Quick review of imitation learning and reinforcement learning
- Visual language navigation
- Instruction following with manipulation and interaction



ALFRED, Shridhar et al, CVPR 2020

- Lots of challenges:
  - Data, task specification, accurate simulation

# Interactive language learning

- Language learning with feedback
  - Human or the environment
- Model weights are adjusted based on feedback





# Text conditioned content generation

- Review of generative models

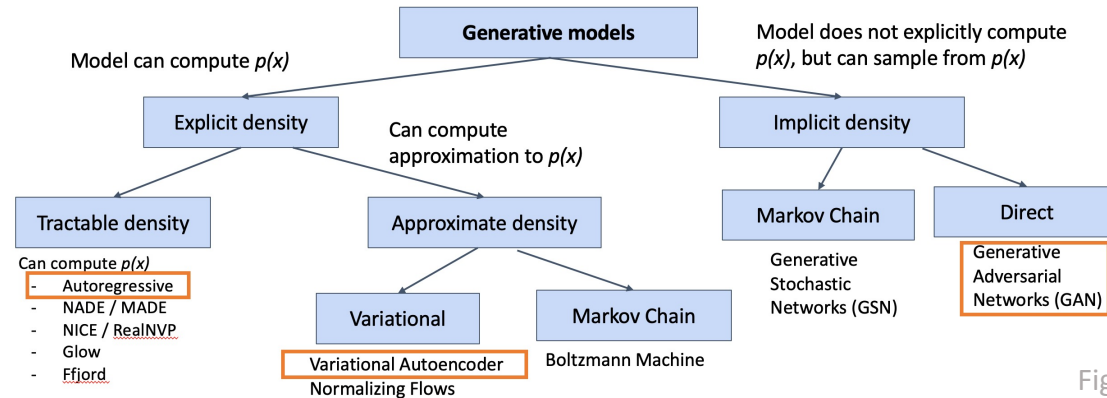


Figure copyright and adapted from Ian Goodfellow, Tutorial on Generative Adversarial Networks, 2017.

- Examples of text-to-image generation with
  - GANs (GAN+CLS+INT, StackGAN++)
  - VAE+Autoregressive (DALL-E – like VQ-VAE but text conditioned)
- Text to 3D is underexplored

# Thank you!

